

Stochastic Processes: Lecture 4

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Point processes

- ▶ A point process is a random list of points $T_i \in \mathcal{T} \subset \mathbb{R}^D$.
- ▶ The total number of points $N(\mathcal{T})$ may be fixed or random.
- ▶ For $A \subset \mathcal{T}$, let $N(A)$ be the total number of points in A :

$$N(A) = \sum_{i=1}^{N(\mathcal{T})} 1\{T_i \in A\}.$$

- ▶ We are interested in *non-explosive* point processes, for which

$$\Pr(N(A) < \infty) = 1 \quad \text{when} \quad \text{vol}(A) < \infty.$$

Poisson processes

- The points $T_i \in \mathcal{T}$ follow a homogeneous poisson process with intensity $\lambda > 0$ if

$$N(A_j) \stackrel{\perp}{\sim} \text{Pois}(\lambda \cdot \text{vol}(A_j))$$

for disjoint sets $A_j \subset \mathcal{T}$ that satisfy $\text{vol}(A_j) < \infty$.

- Define $\lambda(t) : \mathcal{T} \rightarrow [0, \infty)$ so that

$$\int_A \lambda(t) dt < \infty \quad \text{whenever} \quad \text{vol}(A) < \infty.$$

Then for a non-homogeneous point process on \mathcal{T} with intensity function $\lambda(t)$

$$N(A_j) \stackrel{\perp}{\sim} \text{Pois} \left(\int_{A_j} \lambda(t) dt \right)$$

for disjoint sets $A_j \subset \mathcal{T}$ that satisfy $\text{vol}(A_j) < \infty$.

A sampling technique

Theorem 1

Let T_i be the points of a Poisson process on \mathcal{T} with intensity function $\lambda(t) \geq 0$, where $\Lambda(\mathcal{T}) = \int_{\mathcal{T}} \lambda(t) dt$. Then T_i can be sampled by

1. generating $N(\mathcal{T}) \sim \text{Pois}(\Lambda(\mathcal{T}))$ and
2. generating $N(\mathcal{T})$ independent T_i with probabilities

$$\Pr(T_i \in A) = \frac{1}{\Lambda(\mathcal{T})} \int_A \lambda(t) dt.$$

A sampling technique

Proof.

For $J \geq 1$, let A_1, \dots, A_J be disjoint subsets of \mathcal{T} and define $A_0 = \{t \in \mathcal{T} \mid t \notin \cup_{j=1}^J A_j\}$. Let $n_j \geq 0$ for $j = 1, \dots, J$. Let

$$\begin{aligned} P_* &= \Pr(N(A_1) = n_1, \dots, N(A_J) = n_J) \\ &= \sum_{n_0=0}^{\infty} \Pr(N(A_0) = n_0, N(A_1) = n_1, \dots, N(A_J) = n_J). \end{aligned}$$

Set $n = n_0 + n_1 + \dots + n_J$. Under this sampling scheme:

$$\begin{aligned} P_* &= \frac{n!}{n_0! n_1! \dots n_J!} \sum_{n_0=0}^{\infty} \frac{e^{-\Lambda(\mathcal{T})} \Lambda(\mathcal{T})^n}{n!} \prod_{j=0}^J \left(\frac{\Lambda(A_j)}{\Lambda(\mathcal{T})} \right)^{n_j} \\ &= \sum_{n_0=0}^{\infty} \prod_{j=0}^J \frac{e^{-\Lambda(A_j)} \Lambda(A_j)^{n_j}}{n_j!} = \prod_{j=1}^J \frac{e^{-\Lambda(A_j)} \Lambda(A_j)^{n_j}}{n_j!}. \end{aligned}$$

□

A sampling technique

Corollary 1

Let T_i be the points of a homogeneous Poisson process on \mathcal{T} with intensity $\lambda > 0$, where $\text{vol}(\mathcal{T}) < \infty$. Then we may sample the process by

1. generating $N(\mathcal{T}) \sim \text{Pois}(\Lambda(\mathcal{T}))$ and
2. generating $T_i \stackrel{iid}{\sim} \text{Uni}(\mathcal{T})$, $i = 1, \dots, N(\mathcal{T})$.

Proof.

Apply the Theorem with constant $\lambda(t)$. Then

$$\Pr(T_i \in A) = \frac{\lambda \int_A dt}{\lambda \int_{\mathcal{T}} dt} = \text{vol}(A)/\text{vol}(\mathcal{T}).$$

□

Poisson processes on $[0, \infty)$

A Poisson process on $[0, \infty)$ can be represented by the counting function

$$N(t) = N([0, t]) = \sum_{i=1}^{\infty} 1\{T_i \leq t\}, \quad 0 \leq t < \infty.$$

The homogeneous Poisson process on $[0, \infty)$ is defined by these properties:

1. $N(0) = 0$;
2. for $0 \leq s < t$, $N(t) - N(s) \sim \text{Pois}(\lambda(t - s))$;
3. for $0 = t_0 < t_1 < \dots < t_m$, $N(t_i) - N(t_{i-1})$ are independent.

Simulation methods

It can be shown that

$$T_i - T_{i-1} \sim \exp(\lambda), \quad i \geq 1. \quad (1)$$

A heuristic argument says: under (1) and for some x ,

$$\Pr(T_i - T_{i+1} > x) = e^{-\lambda x},$$

but if $T_i - T_{i+1} \geq x$, then the interval $(T_{i-1}, T_{i-1} + x)$ has no events. Under the Poisson model, this probability is

$$f(0; \lambda x) = \frac{(\lambda x)^0 e^{-\lambda x}}{0!} = e^{-\lambda x}.$$

The exponential spacings method simulates a homogeneous Poisson process thus: setting $T_0 = 0$,

$$T_i = T_{i-1} + E_i, \quad E_i \stackrel{iid}{\sim} \exp(\lambda), \quad i \geq 1.$$

Simulation methods

Following previous discussion, we can also simulate a homogeneous Poisson process on $[0, T]$ by

1. generating $N \sim \text{Pois}(\lambda T)$,
2. generating $S_i \stackrel{iid}{\sim} \text{Uni}([0, T])$, $i = 1, \dots, N$, and
3. setting $T_i = S_{(i)}$.

Non-homogeneous Poisson process on $[0, \infty)$

The non-homogeneous Poisson process on $[0, \infty)$ has these properties:

1. $N(0) = 0$;
2. for $0 \leq s < t$, $N(t) - N(s) \sim \text{Pois}\left(\int_s^t \lambda(x) dx\right)$;
3. for $0 = t_0 < t_1 < \dots < t_m$, $N(t_i) - N(t_{i-1})$ are independent.

The cumulative rate function is $\Lambda(t) = \int_0^t \lambda(x) dx$. Start by assuming $\lim_{t \rightarrow \infty} \Lambda(t) = \infty$ and $\lambda(t) > 0, \forall t$. Define variables $Y_i = \Lambda(T_i)$ and the counting function

$$N_y(t) = \sum_{i=1}^{\infty} 1\{Y_i \leq t\} = \sum_{i=1}^{\infty} 1\{T_i \leq \Lambda^{-1}(t)\} = N(\Lambda^{-1}(t)).$$

Non-homogeneous Poisson process on $[0, \infty)$

Define variables $Y_i = \Lambda(T_i)$ and the counting function

$$N_y(t) = \sum_{i=1}^{\infty} 1\{Y_i \leq t\} = \sum_{i=1}^{\infty} 1\{T_i \leq \Lambda^{-1}(t)\} = N(\Lambda^{-1}(t)).$$

Note that $N_y(0) = 0$ and

$$\begin{aligned} N_y(t) - N_y(s) &= N(\Lambda^{-1}(t)) - N(\Lambda^{-1}(s)) \sim \text{Pois} \left(\int_{\Lambda^{-1}(s)}^{\Lambda^{-1}(t)} \lambda(x) dx \right) \\ &= \text{Pois} \left(\Lambda(\Lambda^{-1}(t)) - \Lambda(\Lambda^{-1}(s)) \right) = \text{Pois}(t - s). \end{aligned}$$

Finally the increments of $N_y(t)$ are increments of $N(\Lambda^{-1}(t))$. Independence of the latter implies independence for the former. Therefore,

$$Y_i = \Lambda(T_i) \sim PP(1).$$

More exponential spacings

We have shown $Y_i = \Lambda(T_i) \sim PP(1)$. Setting $Y_0 = T_0 = 0$, we can therefore simulate T_i thus:

$$Y_i = Y_{i-1} + E_i, \quad E_i \stackrel{iid}{\sim} \exp(1), \quad i \geq 1,$$
$$T_i = \Lambda^{-1}(Y_i) = \Lambda^{-1}(\Lambda(T_{i-1}) + E_i).$$

Comments:

- ▶ If $\lim_{t \rightarrow \infty} \Lambda(t) = \Lambda_0$, then $\Lambda^{-1}(y)$ does not exist for $y > \Lambda_0$. If $\Lambda(T_i) + E_i > \Lambda_0$, then there is no T_{i+1} and the process stops.
- ▶ The algorithm is convenient when Λ and Λ^{-1} are available in closed form.
- ▶ The algorithm works even when Λ takes finite jumps or is constant on some intervals by taking

$$\Lambda^{-1}(y) = \inf\{t \geq 0 \mid \Lambda(t) \geq y\}.$$

Thinning (rejection sampling for point processes)

Let $\tilde{\lambda}(t) \geq \lambda(t)$ and assume we can sample from a Poisson process on \mathcal{T} with $\tilde{\lambda}$ for intensity function. The following algorithm generates $(T_1, \dots, T_N) \sim NHPP(\mathcal{T}, \lambda)$:

1. Generate $(\tilde{T}_1, \dots, \tilde{T}_{\tilde{N}}) \sim NHPP(\mathcal{T}, \tilde{\lambda})$;
2. if $\tilde{N} > 0$, then for $i \in \{1, \dots, \tilde{N}\}$:
 - 2.1 draw $u_i \sim \text{Uni}(0, 1)$;
 - 2.2 if $u_i < \rho(\tilde{T}_i) = \lambda(\tilde{T}_i)/\tilde{\lambda}(\tilde{T}_i)$, then $\tilde{T}_i \in \{T_1, \dots, T_N\}$.

Why thinning works

Let $N(A)$ be the number of points T_i in a set A and $\tilde{N}(A)$ be the analogue for points \tilde{T}_i . Note that $\tilde{N}(A) \sim \text{Pois}(\int_A \tilde{\lambda}(t) dt)$. Then the probability a point in $\tilde{T}_i \in A$ is accepted is

$$\rho(A) = \frac{\int_A \rho(t) \tilde{\lambda}(t) dt}{\int_A \tilde{\lambda}(t) dt} = \frac{\int_A \lambda(t) dt}{\int_A \tilde{\lambda}(t) dt}.$$

It holds that $N(A) | \tilde{N}(A) \sim \text{binom}(\tilde{N}(A), \rho(A))$. Marginalizing over $\tilde{N}(A)$ gives

$$N(A) \sim \text{Pois} \left(\rho(A) \int_A \tilde{\lambda}(t) dt \right) = \text{Pois} \left(\int_A \lambda(t) dt \right).$$

Independence of N on non-overlapping sets is inherited from \tilde{N} . Therefore $(T_1, \dots, T_N) \sim \text{NHPP}(\mathcal{T}, \lambda)$.

The temporal Hawkes process

The temporal Hawkes process is a non-homogeneous Poisson process on $[0, \infty)$ with (conditional) intensity function given by

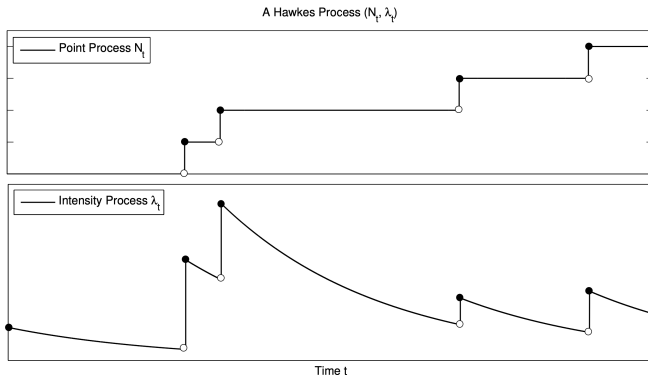
$$\lambda(t|T_k < t) = \lambda_0 + \sum_{T_k < t} g(t - T_k),$$

where $g > 0$ is a non-increasing *triggering function*. Because the intensity increases after an observation, the Hawkes process is referred to as *self-exciting* and is useful for modeling contagion.

Exponential decay

A common choice for g is the exponential decay function:

$$\lambda(t|T_k < t) = \lambda_0 + \alpha \sum_{T_k < t} e^{-\beta(t-T_k)}.$$



Dassios and Zhao, 2013

Figure 1: A Hawkes Process with Exponential Decaying Intensity (N_t, λ_t)

Exponential decay

A common choice for g is the exponential decay function:

$$\lambda(t|T_k < t) = \lambda_0 + \alpha \sum_{T_k < t} e^{-\beta(t-T_k)}.$$

Exponential decay has pros and cons:

- ▶ Pros: exponential decay has computational benefits. Process simulation and likelihood computations are both $O(N)$.
- ▶ Cons: the exponential rate of decay may be too fast for certain applications, precluding long-term dependencies.

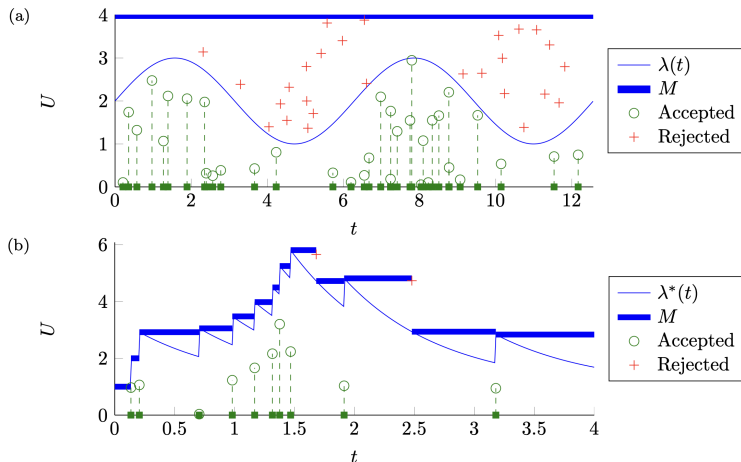
We will return to linear-time computing for the exponential triggering kernel later.

Ogata's modified thinning algorithm

Algorithm 2 Generate a Hawkes process by thinning.

```
1: procedure HAWKESBYTHINNING( $T, \lambda^*(\cdot)$ )
2:   require:  $\lambda^*(\cdot)$  non-increasing in periods of no arrivals.
3:    $\varepsilon \leftarrow 10^{-10}$  (some tiny value  $> 0$ ).
4:    $P \leftarrow []$ ,  $t \leftarrow 0$ .
5:   while  $t < T$  do
6:     Find new upper bound:
7:      $M \leftarrow \lambda^*(t + \varepsilon)$ .
8:     Generate next candidate point:
9:      $E \leftarrow \text{Exp}(M)$ ,  $t \leftarrow t + E$ .
10:    Keep it with some probability:
11:     $U \leftarrow \text{Unif}(0, M)$ .
12:    if  $t < T$  and  $U \leq \lambda^*(t)$  then
13:       $P \leftarrow [P, t]$ .
14:    end if
15:  end while
16:  return  $P$ 
17: end procedure
```

Ogata's modified thinning algorithm



Conditional intensity and stochastic calculus

For the counting process $N(t)$ with histories $\mathcal{H}(t)$, we can define our conditional intensity

$$\lambda(t) = \lim_{h \rightarrow 0} \frac{E(N(t+h) - N(t) | \mathcal{H}(t))}{h} = \frac{E(dN(t) | \mathcal{H}(t))}{dt}$$

and for a general Hawkes process we have

$$\lambda(t) = \lambda_0 + \int_0^t g(t-u) dN(u).$$

When g specifies exponential decay, this becomes

$$\lambda(t) = \lambda_0 + \alpha \int_0^t e^{-\beta(t-u)} dN(u),$$

or

$$d\lambda(t) = \beta(\lambda_0 - \lambda(t))dt + \alpha dN(t).$$

Asymptotic normality of Hawkes process

Theorem 2

Assume $0 < n := \int_0^\infty g(s)ds < 1$ and $\int_0^\infty sg(s)ds < \infty$, then the number of HP arrivals in $(0, t]$ is asymptotically normally distributed as $t \rightarrow \infty$, i.e.,

$$\Pr\left(\frac{N(0, t] - \lambda_0 t(1 - n)^{-1}}{\sqrt{\lambda_0 t(1 - n)^{-3}}} < y\right) \rightarrow \Phi(y).$$

Note that for the exponential Hawkes model we only have a CLT when $\alpha/\beta < 1$:

$$n = \int_0^\infty g(s)ds = \alpha \int_0^\infty e^{-\beta s} ds = \frac{\alpha}{\beta}.$$

Stationarity and explosiveness

Again, let $n := \int_0^\infty g(s)ds$ and define

$$\begin{aligned}m(t) &= E(\lambda(t)) = E\left(\lambda_0 + \int_0^t g(t-u)dN(u)\right) \\ &= \lambda_0 + \int_0^t g(t-u) E(dN(u)).\end{aligned}$$

But

$$\lambda(t) = \lim_{h \rightarrow 0} \frac{E(N(t+h) - N(t) | \mathcal{H}(t))}{h} = \frac{E(dN(t) | \mathcal{H}(t))}{dt},$$

so by iterated expectation

$$m(t) = E(\lambda(t)) = E\left(\frac{E(dN(t) | \mathcal{H}(t))}{dt}\right) = \frac{E(dN(t))}{dt}$$

and $m(t)dt = E(dN(t))$. Thus we obtain the recursion

$$m(t) = \lambda + \int_0^t g(t-s)m(s)ds = \lambda + \int_0^t m(t-s)g(s)ds.$$

When $n < 1$, $g(t) \rightarrow \lambda/(1-n)$, but when $n > 1$, $g(t)$ diverges to infinity.

More exponential Hawkes process

Definition 1 (Intensity-based)

A Hawkes process with exponentially decaying intensity is a Poisson process $N_t = \{T_k\}_{k=1,2,\dots}$ on \mathbb{R}_+ with non-negative \mathcal{F}_t -stochastic intensity

$$\lambda_t = a + (\lambda_0 - a)e^{-\delta t} + \sum_{0 \leq T_k < t} Y_k e^{-\delta(t-T_k)}, \quad t \geq 0,$$

where:

- ▶ $\{\mathcal{F}_t\}_{t \geq 0}$ is a history of the process w.r.t.w. $\{\lambda_t\}_{t \geq 0}$ is adapted;
- ▶ $a \geq 0$ is the constant reversion level;
- ▶ $\lambda_0 > 0$ is the initial intensity at time $t = 0$;
- ▶ $\delta > 0$ is the rate of exponential decay;
- ▶ $\{Y_k\}_{k=1,2,\dots}$ are positive random variables that are i.i.d. with distribution function $G(y)$;
- ▶ $\{T_k\}_{k=1,2,\dots}$ and $\{Y_k\}_{k=1,2,\dots}$ are mutually independent.

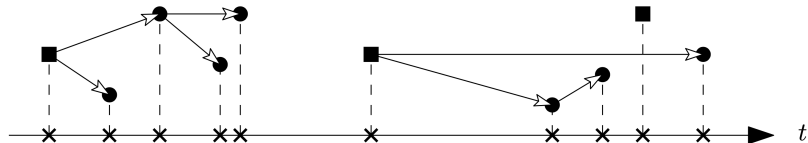
More exponential Hawkes process

Definition 2 (Cluster-based)

A Hawkes process with exponentially decaying intensity is a marked Poisson cluster process $C = \{T_i, Y_i\}_{i=1,2,\dots}$ with times $T_i \in \mathbb{R}_+$ and marks Y_i : the number of points in $(0, t]$ is defined $N_t = N_{C(0,t]}$; the cluster centers of C are 'immigrants', the rest are 'offspring', and they share the following structure:

- ▶ the immigrants $I = \{T_m\}_{m=1,2,\dots}$ are distributed as an NHPP with rate $a + (\lambda_0 - a)e^{-\delta t}$;
- ▶ the marks $\{Y_m\}_{m=1,2,\dots}$ associated to immigrants I are i.i.d. $Y_m \sim G(y)$ and are independent of the immigrants;
- ▶ each immigrant T_m generates one cluster C_m , and these clusters are independent;
- ▶ each cluster C_m is a random set formed by marked points of generations of order $n = 0, 1, \dots$ with the following branching structure
 - ▶ the immigrant and its mark (T_m, Y_m) are generation 0;
 - ▶ given generations $0, 1, \dots, n$ in C_m each $(T_j, Y_j) \in C_m$ of generation n generates are a Poisson process on (T_j, ∞) with intensity $Y_j \exp(-\delta(t - T_j))$, with $Y_j \sim G$ independent.
- ▶ C consists of the union of all clusters, i.e., $C = \bigcup_{m=1,2,\dots} C_m$.

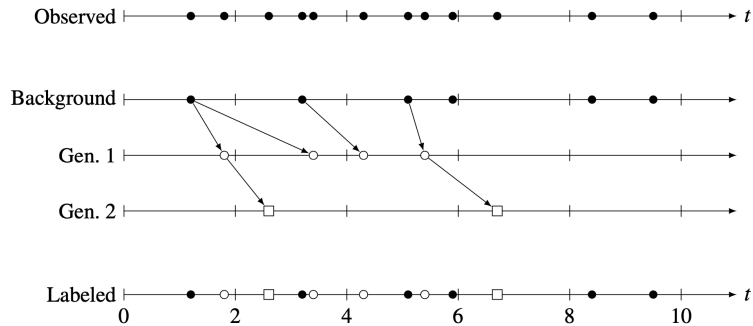
Cluster-based representation



Laub et al., 2015

- ▶ The cluster-based or *branching process* definition is equivalent to the intensity-based definition.
- ▶ The cluster representation can be used to simulate a Hawkes process just as we have used the intensity representation to simulate.
- ▶ The equivalent representations hold beyond exponential HP.

Cluster-based representation



Explosion and cluster-based representation

Conditioned on knowing the number of children in a generation (say, D_1), the generation's arrival times are distributed i.i.d. with density $g(t - T_i)/n$. Note that for the exponential Hawkes process, we have

$$g(t - T_i)/n = \beta e^{-\beta(t - T_i)}.$$

The expected total number of children in generation i is $E(D_i) = n^i$, so the expected total number of children for one individual is

$$E\left(\sum_{i=1}^{\infty} D_i\right) = \sum_{i=1}^{\infty} E(D_i) = \sum_{i=1}^{\infty} n^i = \begin{cases} \frac{n}{1-n}, & n < 1 \\ \infty, & n \geq 1 \end{cases}.$$

When $n < 1$, it is the ratio between the number of descendants for one parent and the size of the entire family (including the parent):

$$\frac{E\left(\sum_{i=1}^{\infty} D_i\right)}{1 + E\left(\sum_{i=1}^{\infty} D_i\right)} = \frac{\frac{n}{1-n}}{1 + \frac{n}{1-n}} = \frac{\frac{n}{1-n}}{\frac{1}{1-n}} = n,$$

therefore any HP event chosen at random is generated *exogenously* (an immigrant) with probability $1 - n$ or *endogenously* (a child) with probability n .

An incorrect cluster-based simulation algorithm

Algorithm 3 Generate a Hawkes process by clusters.

```
1: procedure HAWKESBYCLUSTERS( $T, \lambda, \alpha, \beta$ )
2:    $P \leftarrow \{\}$ .
3:   Immigrants:
4:      $k \leftarrow \text{Poi}(\lambda T)$ 
5:      $C_1, C_2, \dots, C_k \stackrel{\text{i.i.d.}}{\leftarrow} \text{Unif}(0, T)$ .
6:   Descendants:
7:      $D_1, D_2, \dots, D_k \stackrel{\text{i.i.d.}}{\leftarrow} \text{Poi}(\alpha/\beta)$ .
8:   for  $i \leftarrow 1$  to  $k$  do
9:     if  $D_i > 0$  then
10:        $E_1, E_2, \dots, E_{D_i} \stackrel{\text{i.i.d.}}{\leftarrow} \text{Exp}(\beta)$ .
11:        $P \leftarrow P \cup \{C_i + E_1, \dots, C_i + E_{D_i}\}$ .
12:     end if
13:   end for
14:   Remove descendants outside  $[0, T]$ :
15:    $P \leftarrow \{P_i : P_i \in P, P_i \leq T\}$ .
16:   Add in immigrants and sort:
17:    $P \leftarrow \text{Sort}(P \cup \{C_1, C_2, \dots, C_k\})$ .
18:   return  $P$ 
19: end procedure
```

More exponential Hawkes process

Definition 3 (Intensity-based)

A Hawkes process with exponentially decaying intensity is a Poisson process $N_t = \{T_k\}_{k=1,2,\dots}$ on \mathbb{R}_+ with non-negative \mathcal{F}_t -stochastic intensity

$$\lambda_t = a + (\lambda_0 - a)e^{-\delta t} + \sum_{0 \leq T_k < t} Y_k e^{-\delta(t-T_k)}, \quad t \geq 0,$$

where:

- ▶ $\{\mathcal{F}_t\}_{t \geq 0}$ is a history of the process w.r.t.w. $\{\lambda_t\}_{t \geq 0}$ is adapted;
- ▶ $a \geq 0$ is the constant reversion level;
- ▶ $\lambda_0 > 0$ is the initial intensity at time $t = 0$;
- ▶ $\delta > 0$ is the rate of exponential decay;
- ▶ $\{Y_k\}_{k=1,2,\dots}$ are positive random variables that are i.i.d. with distribution function $G(y)$;
- ▶ $\{T_k\}_{k=1,2,\dots}$ and $\{Y_k\}_{k=1,2,\dots}$ are mutually independent.

A fast simulation method

A simulation algorithm for one sample path $\{N_t, \lambda_t\}_{t=0,1,\dots}$ of a 1D exponential Hawkes process conditional on λ_0 and $N_0 = 0$, with jump distribution G and K jump times $\{T_1, \dots, T_K\}$:

1. set the initial conditions $T_0 = 0$, $\lambda_{T_0^\pm} = \lambda_0 > a$, $N_0 = 0$ and $k \in \{0, 1, \dots, K-1\}$;
2. simulate the $(k+1)$ th inter-arrival time S_{k+1} by

$$S_{k+1} = \begin{cases} S_{k+1}^{(1)} \wedge S_{k+1}^{(2)}, & D_{k+1} > 0 \\ S_{k+1}^{(2)}, & D_{k+1} < 0 \end{cases},$$

where

$$D_{k+1} = 1 + \frac{\delta \ln U_1}{\lambda_{T_k^+} - a} \quad U_1 \sim U(0, 1),$$

and

$$S_{k+1}^{(1)} = -\frac{1}{\delta} \ln D_{k+1}, \quad S_{k+1}^{(2)} = -\frac{1}{a} \ln U_2, \quad U_2 \sim U(0, 1);$$

A fast simulation method

- record the $(k + 1)$ th jump time

$$T_{k+1} = T_k + S_{k+1};$$

- record the change in the intensity at time T_{k+1} by

$$\lambda_{T_{k+1}^+} = \lambda_{T_{k+1}^-} + Y_{k+1}, \quad Y_{k+1} \sim G,$$

where

$$\lambda_{T_{k+1}^-} = \left(\lambda_{T_k^+} - a \right) e^{-\delta(T_{k+1} - T_k)} + a;$$

- record the change in the in process N_t by

$$N_{T_{k+1}^+} = N_{T_{k+1}^-} + 1.$$

Proof.

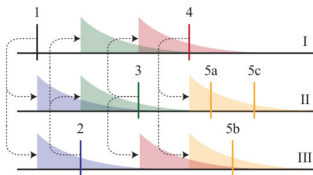
On the whiteboard...



Multivariate Hawkes process

Consider the D -dimensional point process $\{N_t^{[d]}\}_{d=1}^D$, where $N_t^{[d]} \equiv \{T_k^{[d]}\}_{k=1,2,\dots}$ with the underlying intensity process

$$\lambda_t^{[d]} = a^{[d]} + \left(\lambda_0^{[d]} - a^{[d]} \right) e^{-\delta^{[d]}t} + \sum_{\ell=1}^D \sum_{T_k^{[\ell]} < t} Y_k^{[d,\ell]} e^{-\delta^{[d,\ell]}(t-T_k^{[\ell]})}.$$



Lemonnier et al., 2016

We call this process a *multivariate Hawkes process* or *mutually exciting Hawkes processes*. These can also be simulated using a similar algorithm but taking the next inter-arrival time as

$$S_{k+1} = \min\{S_{k+1}^{[1]}, \dots, S_{k+1}^{[D]}\}.$$

Conditional intensity as hazard function

Given the history up until the last arrival u , $\mathcal{H}(u)$, define the conditional c.d.f. and p.d.f. of the next arrival time T_{k+1}

$$F(t|\mathcal{H}(u)) = \int_u^t \Pr(T_{k+1} \in [s, s + ds]|\mathcal{H}(u))ds = \int_u^t f(s|\mathcal{H}(u))ds.$$

The joint p.d.f. of a realization $\{t_1, t_2, \dots, t_k\}$ is

$$f(t_1, t_2, \dots, t_k) = \prod_{i=1}^k f(t_i|\mathcal{H}(t_{i-1})).$$

The shorthand notations $f^*(t) = f(t|\mathcal{H}(u))$ and $F^*(t) = F(t|\mathcal{H}(u))$ are common. The conditional intensity can be characterized as the hazard function

$$\lambda(t) = \frac{f^*(t)}{1 - F^*(t)}.$$

Hawkes process likelihood

Theorem 3

Let $N(\cdot)$ be a regular point process on $[0, T]$ for some positive $T < \infty$ and let t_1, t_2, \dots, t_k denote a realization of $N(\cdot)$ over $[0, T]$. Then the likelihood L of $N(\cdot)$ is expressible as

$$L = \left(\prod_{i=1}^k \lambda(t_i) \right) \exp \left(- \int_0^T \lambda(t) dt \right) = \left(\prod_{i=1}^k \lambda(t_i) \right) e^{-\Lambda(T)}.$$

Hawkes process likelihood

Assume process observed to time of k th arrival. The joint density is

$$L = f(t_1, \dots, t_k) = \prod_{i=1}^k f^*(t_i).$$

Rearrange hazard function definition of $\lambda(t)$

$$\lambda(t) = \frac{f^*(t)}{1 - F^*(t)} = \frac{\frac{dF^*(t)}{dt}}{1 - F^*(t)} = -\frac{d \log(1 - F^*(t))}{dt}$$

and integrate both sides over the interval (t_k, t)

$$-\int_{t_k}^t \lambda(u) du = \log(1 - F^*(t)) - \log(1 - F^*(t_k)).$$

But $F^*(t_k) = 0$ because $T_{k+1} > t_k$, so

$$F^*(t) = 1 - \exp\left(-\int_{t_k}^t \lambda(u) du\right) \quad \text{and} \quad f^*(t) = \lambda(t) \exp\left(-\int_{t_k}^t \lambda(u) du\right).$$

Hawkes process likelihood

So far, we have

$$L = f(t_1, \dots, t_k) = \prod_{i=1}^k f^*(t_i)$$

and

$$F^*(t) = 1 - \exp\left(-\int_{t_k}^t \lambda(u) du\right) \quad \text{and} \quad f^*(t) = \lambda(t) \exp\left(-\int_{t_k}^t \lambda(u) du\right).$$

Now suppose the process is observed to some time $T > t_k$. Then the likelihood includes the probability of not observing anything on the interval $(t_k, T]$:

$$\begin{aligned} L &= (1 - F^*(T)) \prod_{i=1}^k f^*(t_i) = \exp\left(-\int_{t_k}^T \lambda(u) du\right) \prod_{i=1}^k f^*(t_i) \\ &= \left(\prod_{i=1}^k \lambda(t_i) \exp\left(-\int_{t_{i-1}}^{t_i} \lambda(u) du\right)\right) \exp\left(-\int_{t_k}^T \lambda(u) du\right) \\ &= \left(\prod_{i=1}^k \lambda(t_i)\right) e^{-\Lambda(T)}. \end{aligned}$$

Exponential Hawkes process likelihood

The log-likelihood for the interval $[0, t_k]$ can be written

$$\ell = -\Lambda(t_k) + \sum_{i=1}^k \log(\lambda(t_i)),$$

and $\Lambda(t_k)$ can be written

$$\Lambda(t_k) = \int_0^{t_1} \lambda(u) du + \sum_{i=1}^{k-1} \int_{t_i}^{t_{i+1}} \lambda(u) du.$$

For the exponential Hawkes process, this becomes

$$\begin{aligned}\Lambda(t_k) &= \int_0^{t_1} \lambda du + \sum_{i=1}^{k-1} \int_{t_i}^{t_{i+1}} \lambda + \sum_{t_j < u} \alpha e^{-\beta(u-t_j)} du \\ &= \lambda t_k + \alpha \sum_{i=1}^{k-1} \int_{t_i}^{t_{i+1}} \sum_{j=1}^i e^{-\beta(u-t_j)} du \\ &= \lambda t_k + \alpha \sum_{i=1}^{k-1} \sum_{j=1}^i \int_{t_i}^{t_{i+1}} e^{-\beta(u-t_j)} du\end{aligned}$$

Exponential Hawkes process likelihood

Continuing, we have

$$\begin{aligned}\Lambda(t_k) &= \lambda t_k + \alpha \sum_{i=1}^{k-1} \sum_{j=1}^i \int_{t_j}^{t_{i+1}} e^{-\beta(u-t_j)} du \\ &= \lambda t_k - \frac{\alpha}{\beta} \sum_{i=1}^{k-1} \sum_{j=1}^i \left(e^{-\beta(t_{i+1}-t_j)} - e^{-\beta(t_i-t_j)} \right) \\ &= \lambda t_k - \frac{\alpha}{\beta} \sum_{i=1}^{k-1} \left(e^{-\beta(t_k-t_i)} - e^{-\beta(t_i-t_i)} \right) \\ &= \lambda t_k - \frac{\alpha}{\beta} \sum_{i=1}^{k-1} \left(e^{-\beta(t_k-t_i)} - 1 \right) .\end{aligned}$$

Thus, the log-likelihood can be written

$$\ell = -\lambda t_k + \sum_{i=1}^k \left(\log \left(\lambda + \alpha \sum_{j=1}^{i-1} e^{-\beta(t_i-t_j)} \right) + \frac{\alpha}{\beta} \left(e^{-\beta(t_k-t_i)} - 1 \right) \right) .$$

Exponential Hawkes process likelihood

The log-likelihood

$$\ell = -\lambda t_k + \sum_{i=1}^k \left(\log \left(\lambda + \alpha \sum_{j=1}^{i-1} e^{-\beta(t_i - t_j)} \right) + \frac{\alpha}{\beta} \left(e^{-\beta(t_k - t_i)} - 1 \right) \right).$$

has quadratic computational complexity $O(k^2)$, but a recursion turns it into linear complexity $O(k)$. For $i = 2, \dots, k$, let $A(i) = \sum_{j=1}^{i-1} e^{-\beta(t_i - t_j)}$. Then

$$\begin{aligned} A(i) &= e^{-\beta t_i + \beta t_{i-1}} \sum_{j=1}^{i-1} e^{-\beta t_{i-1} + \beta t_j} = e^{-\beta(t_i - t_{i-1})} \left(1 + \sum_{j=1}^{i-2} e^{-\beta(t_{i-1} - t_j)} \right) \\ &= e^{-\beta(t_i - t_{i-1})} (1 + A(i-1)). \end{aligned}$$

Letting $A(1) = 0$, the log-likelihood can be written

$$\ell = -\lambda t_k + \sum_{i=1}^k \left(\log(\lambda + \alpha A(i)) + \frac{\alpha}{\beta} \left(e^{-\beta(t_k - t_i)} - 1 \right) \right).$$

Similar recursions are also available for the log-likelihood gradient.

Nonlinear Hawkes process

Letting $\Psi : \mathbb{R} \rightarrow \mathbb{R}_+$ be an arbitrary function, a nonlinear Hawkes process has conditional intensity function

$$\lambda(t) = \Psi \left(\int_0^t g(t-u) dN(u) \right) .$$

The linear Hawkes process is a special case. One may incorporate inhibition by specifying, say,

$$\lambda(t) = \exp \left(\mu t - \int_0^t g(t-u) dN(u) \right) .$$

Recently, autoregressive neural networks (RNN, transformer NN) have been used to model the function Ψ .

Spatiotemporal Hawkes processes

- ▶ Spatiotemporal Hawkes processes are useful for modeling earthquakes, wildfires, viral contagion and gun violence.
- ▶ The conditional intensity models the rate of events at locations $s \in X \subset \mathbb{R}^D$:

$$\lambda(s, t | \mathcal{H}(t)) = \lim_{\Delta s, \Delta t \rightarrow 0} \frac{E(N(B(s, \Delta s) \times [t, t + \Delta t]) | \mathcal{H}(t))}{|B(s, \Delta s)| \Delta t}.$$

- ▶ For $\{(s_1, t_1), \dots, (s_k, \dots, t_k)\}$ observed, a spatiotemporal Hawkes process has conditional intensity

$$\lambda(s, t) = \mu(s) + \sum_{t_i < t} g(s - s_i, t - t_i),$$

where the triggering function g is non-negative.

- ▶ The spatiotemporal HP also has a cluster process representation with mean number of children for each event

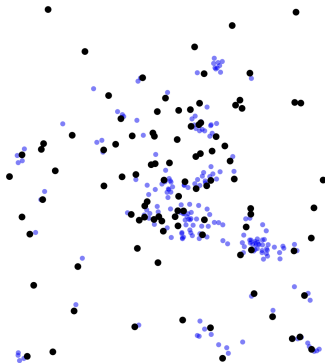
$$n = \int_X \int_0^T g(s, t) ds dt.$$

Spatiotemporal Hawkes processes

Inhomogeneous process



Self-exciting process



Spatiotemporal Hawkes process

The log-likelihood for the spatiotemporal Hawkes process takes a similar form to that of the temporal Hawkes process:

$$\begin{aligned}\ell &= \sum_{i=1}^k \log(\lambda(s_i, t_i)) - \int_X \int_0^T \lambda(s, t) ds dt \\ &= \sum_{i=1}^k \log \left(\mu(s) + \sum_{t_j < t} g(s_i - s_j, t_i - t_j) \right) \\ &\quad - \int_X \int_0^T \mu(s) + \sum_{t_j < t} g(s - s_j, t - t_j) ds dt .\end{aligned}$$

The double summation in the first term implies an $O(k^2)$ computational complexity for k observations. No linear-time recursion is known. In EM/MCMC, it can be helpful to use the (still $O(k^2)$) 'complete data likelihood'

$$\begin{aligned}\ell_c &= \sum_{i=1}^k \mathbf{1}\{u_i = 0\} \log(\mu(s_i)) + \sum_{i=1}^k \sum_{j=1}^k \mathbf{1}\{u_i = j\} \log(g(s_i - s_j, t_i - t_j)) \\ &\quad - \int_X \int_0^T \lambda(s, t) ds dt .\end{aligned}$$

Simulating the spatiotemporal Hawkes process

- ▶ Ogata (1998) proposes a two-stage algorithm that (1) simulates the temporal HP obtained by integrating over space and (2) simulates from the spatial inhomogeneous PP for each timepoint.
- ▶ Zhuang, Ogata and Vere-Jones (2004) propose a cluster based algorithm.

Simulating the spatiotemporal Hawkes process

Again, define the branching number $n = \int_{\mathcal{X}} \int_0^T g(s, t) ds dt$. The following algorithm simulates a sample path of a spatiotemporal Hawkes process.

1. Generate events from the background process with intensity $\mu(s)$ using a method for simulating NHPP (e.g., thinning). Call events $G^{(0)}$;
2. let $l = 0$;
3. For each event $i \in G^{(l)}$, simulate the number of offspring $O_i^{(l)}$ $N^{(i)} \sim \text{Pois}(n)$ and the position/time of each with the normalized g as distribution.
4. Let $G^{(l+1)} = \bigcup_{i \in G^{(l)}} O_i^{(l)}$
5. If $G^{(l+1)}$ not empty, let $l = l + 1$ and return to step 3. Otherwise, return $\bigcup_{j=0}^l G^{(j)}$.